

Human Exploration Systems and Mobility Capability Roadmap Development

Dec. 2004



Team Charter

- This roadmap covers a variety of areas that deal with human elements of exploration. Rather than a cohesive theme, this team captures elements that don't appear to fall under any other roadmap domain.
 - Crew Mobility
 - In-Space Assembly
 - In-Space System Deployment
 - Servicing, Maintenance and Repair
 - Human Science Activities



Relevance

- Human participation in exploration missions is an essential element of the vision for NASA's future.
- Core capabilities such as In-space assembly, crew mobility, and human science need further development to be able to meet anticipated future needs.
 - Lowered ops costs
 - Larger scale missions
 - Improved ROI for science
 - Higher probability of mission success



1.0 Crew Mobility

- 1.1 Surface Mobility
- 1.2 In Space Mobility

2.0 In-Space Assembly

- 2.1 Systems for In-Space Assembly and Inspection Prep and Execution
- 2.2 Large Scale Assembly Systems
- 2.3 Intermediate Scale Assembly Systems
- 2.4 Fine Scale Assembly Systems
- 2.5 Metrology and Positioning
- 2.6 Intra-Vehicular Assembly and Construction
- 2.7 Logistics and Planning for Assembly
- 2.8 Architectures for Human-Robot Teams



or in space system beproymen	3.0	In-Space	System	Deploymen	t
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3.1	Kinematically-Deployable Systems
3.2	Inflatable Systems
3.3	Deployable Intermediate Precision Systems
3.4	Deployable High Precision Systems
3.5	Structural and Pressurized Interconnections
3.6	Electrical and Data Interconnections
3.7	Thermal and Fluid Interconnections
3.8	Release and Latch-up Systems
3.9	Docking Controls, Mechanisms & Actuators
3.10	Pressurized Module Docking Control and Mechanisms
3.11	Adaptive Self-Assembling System Architectures



4.0	Servicii	ig, Maintenance and Repair
	4.1	Extra-Vehicular Inspection

- **4.2** Non-Destructive Evaluation and Test
- 4.3 Outgassing, Leak & Contamination Detection
- 4.4 Electronics Fault Detection, Isolation & Diagnosis
- 4.5 Software Fault Detection, Isolation and Diagnosis
- 4.6 Modular Subsystem and Component Replacement Units
- 4.7 Rescue and Intrusive Repairs
- 4.8 Propulsion System Refurbishment and Repair
- 4.9 Refueling and Fluids Resupply Support Systems
- 4.10 Structural Materials-Level Repair Systems
- 4.11 Upgradeable and Reconfigurable Systems Concepts
- 4.12 Standards, Interfaces and Architectures



- 5.0 Human Science Activities (includes both basic and applied science)
 - 5.1 Field tools
 - 5.2 Tools to repair and monitor resource extraction experiments
 - 5.3 Laboratory equipment (highly automated)
 - 5.4 Rover payloads (instruments, tools as above, sample transport)
 - 5.5 Science via telerobotics
 - **5.5.1** Teleoperated field geologists (telepresence)
 - 5.5.2 Payload (instruments, sampling tools, etc.)
 - 5.5.3 Rover repair



Roadmap Events and Schedule

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 Week of Dec 6 	Finalize team formation
• Week of Dec. 13	Telecon with full team
• Week of Jan 3	Telecon with full team
• Week of Jan 10	Telecon with full team
• Week of Jan 17	Full team face to face in Houston
 Week of Jan 24 	
• Week of Jan 31	Telecon with full team
 Week of Feb 7 	
 Week of Feb 14 	Full team face to face in TBD location
 Week of Feb 21 	
 Week of Feb 28 	Telecon with full team
- Mar. 4 th	Draft Roadmap ready
• Week of Mar 7	Telecon with full team
 Week of Mar 14 	
– Mar 15	NRC Draft presentation ready
– Mar 18	Final Roadmap ready
 Week of Mar 21 	Telecon with full team
- Mar 25	Final NRC presentation ready
 Week of Mar 28 	Presentation to NRC, in TBD location

Backup Slides



Human Exploration Systems and Mobility Capability Team

Chair: Chris Culbert, NASA/Johnson

Co-Chair: Jeff Taylor, Univ. of Hawaii